Advanced Card Systems Ltd.
Card & Reader Technologies

ACR1251U-A1 USB NFC Reader with SAM

Application Programming Interface V1.00

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1.0. Introduction

The ACR1251U-A1 is a PC-linked NFC smart card reader developed based on the 13.56 MHz contactless technology. Following the ACR122U, ACS's successful NFC reader and also the world's first CCID-compliant contactless reader, the ACR1251U-A1 offers more and advanced features. It is designed to support not only ISO 14443 Type A and B cards, but also Mifare, FeliCa and all four types of NFC tags and devices.

ACR1251U-A1 acts as the intermediary device between the PC and the card. The reader, specifically to communicate with a contactless tag, SAM card or the device peripherals (LED or buzzer), will carry out a command issued from the PC. It has two reader interfaces, namely the PICC and SAM interface, and both interface follow the PC/SC specifications. This API document will discuss in details how the PC/SC APDU commands were implemented for the contactless interface and device peripherals of ACR1251U-A1.

2.0. Features

- USB 2.0 Full Speed Interface
- CCID Compliance
- Smart Card Reader:
  - Read/Write speed of up to 424 kbps
  - Built-in antenna for contactless tag access, with card reading distance of up to 50 mm (depending on tag type)
  - Support for ISO 14443 Part 4 Type A and B cards, Mifare, FeliCa, and all four types of NFC (ISO/IEC 18092 tags)
  - Built-in anti-collision feature (only one tag is accessed at any time)
  - NFC Support:
    - Card reader/writer mode
    - Peer-to-Peer mode
  - ISO 7816-compliant SAM slot
- Application Programming Interface:
  - Supports PC/SC
  - Supports CT-API (through wrapper on top of PC/SC)
- Built-in Peripherals:
  - User-controllable bi-color LED
  - User-controllable buzzer
- USB Firmware Upgradability
- Supports Android™ OS 3.1 and above
- Compliant with the following standards:
  - ISO 14443
  - CE
  - FCC
  - VCCI
  - PC/SC
  - CCID
  - Microsoft® WHQL
  - RoHS

3.0. Architecture

For communication architecture, the protocol used between ACR1251U reader and the computer is CCID protocol. All communications between PICC and SAM are PCSC-compliant.

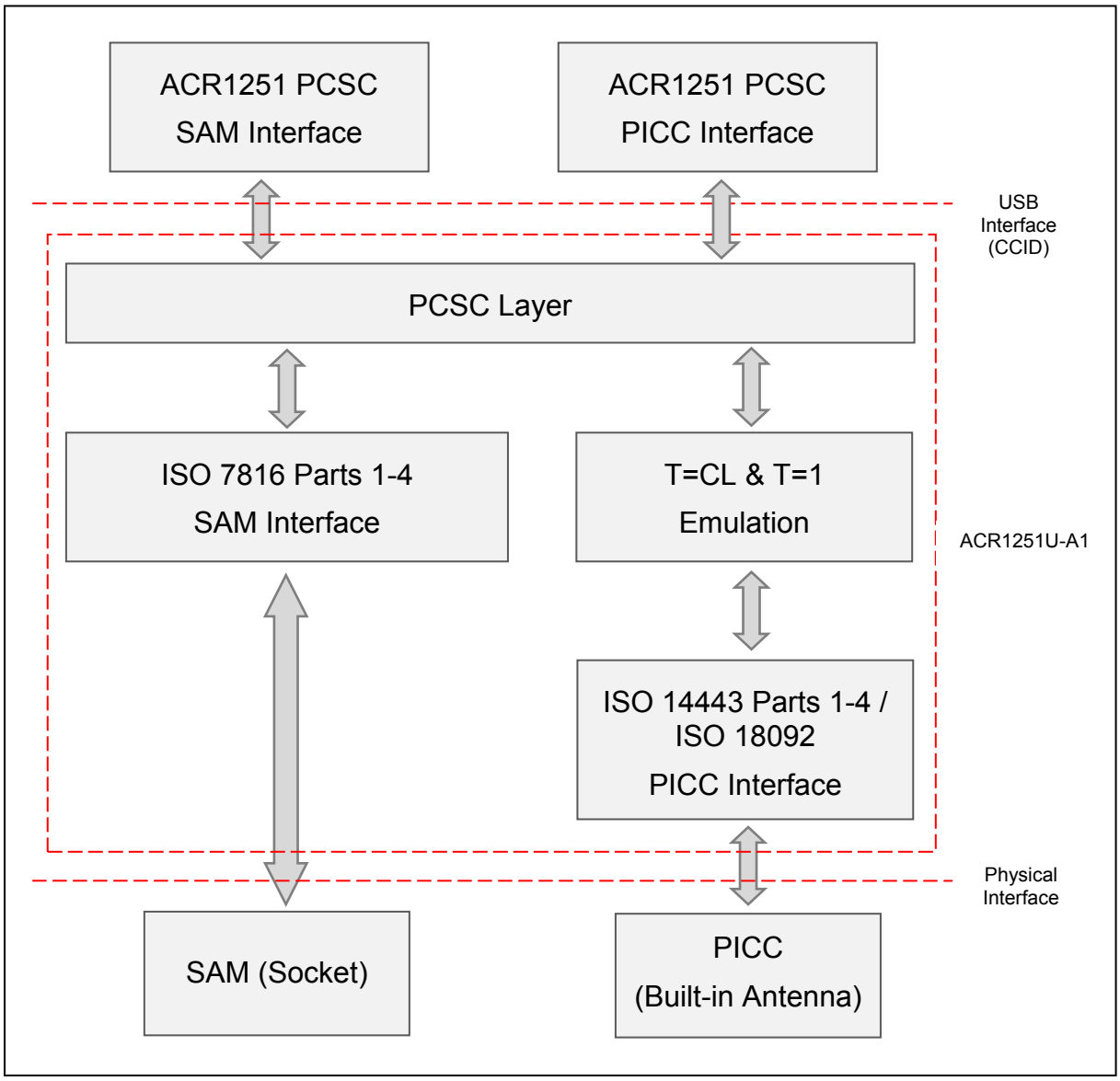


Figure 1: ACR1251U-A1 Architecture

4.0. Software Design

4.1. Contactless Smart Card Protocol

4.1.1. ATR Generation

If the reader detects a PICC, an ATR will be sent to the PCSC driver for identifying the PICC.

4.1.1.1. ATR Format for ISO 14443 Part 3 PICCs

Byte	Value	Designation	Description
0	3Bh	Initial Header	
1	8Nh	T0	Higher nibble 8 means: no TA1, TB1, TC1 only TD1 is following. Lower nibble N is the number of historical bytes (HistByte 0 to HistByte N-1)
2	80h	TD1	Higher nibble 8 means: no TA2, TB2, TC2 only TD2 is following. Lower nibble 0 means T = 0
3	01h	TD2	Higher nibble 0 means no TA3, TB3, TC3, TD3 following. Lower nibble 1 means T = 1
4 To 3+N	80h	T1	Category indicator byte, 80 means A status indicator may be present in an optional COMPACT-TLV data object.
	4Fh	Tk	Application identifier Presence Indicator.
	0Ch		Length
	RID		Registered Application Provider Identifier (RID) # A0 00 00 03 06
	SS		Byte for standard.
	C0 .. C1h		Bytes for card name.
	00 00 00 00h	RFU	RFU # 00 00 00 00
4+N	UU	TCK	Exclusive-oring of all the bytes T0 to Tk

Example:

ATR for Mifare 1K = {3B 8F 80 01 80 4F 0C A0 00 00 03 06 03 00 01 00 00 00 00 6Ah}

Where:

Length (YY) = 0Ch

RID = A0 00 00 03 06h (PC/SC Workgroup)

Standard (SS) = 03h (ISO 14443A, Part 3)

Card Name (C0 .. C1) = [00 01h] (Mifare 1K)

Standard (SS) = 03h: ISO 14443A, Part 3

	= 11h: FeliCa	
Card Name (C0 .. C1)	00 01: Mifare 1K	00 30: Topaz and Jewel
	00 02: Mifare 4K	00 3B: FeliCa
	00 03: Mifare Ultralight	FF 28: JCOP 30
	00 26: Mifare Mini	FF [SAK]: undefined tags

4.1.1.2. ATR Format for ISO 14443 Part 4 PICCs

<table>
<tr><th>Byte</th><th>Value</th><th>Designation</th><th>Description</th></tr>
<tr><td>0</td><td>3Bh</td><td>Initial Header</td><td></td></tr>
<tr><td>1</td><td>8N</td><td>T0</td><td>Higher nibble 8 means: no TA1, TB1, TC1 only TD1 is following.
Lower nibble N is the number of historical bytes (HistByte 0 to HistByte N-1)</td></tr>
<tr><td>2</td><td>80h</td><td>TD1</td><td>Higher nibble 8 means: no TA2, TB2, TC2 only TD2 is following.
Lower nibble 0 means T = 0</td></tr>
<tr><td>3</td><td>01h</td><td>TD2</td><td>Higher nibble 0 means no TA3, TB3, TC3, TD3 following.
Lower nibble 1 means T = 1</td></tr>
<tr><td rowspan="2">4
to
3 + N</td><td>XX</td><td>T1</td><td rowspan="2">Historical Bytes:

ISO 14443A:
The historical bytes from ATS response. Refer to the ISO 14443-4 specification.

ISO 14443B:<table><tr><th>Byte1-4</th><th>Byte5-7</th><th>Byte8</th></tr><tr><td>Application Data from ATQB</td><td>Protocol Info Byte from ATQB</td><td>Higher nibble=MBLI from ATTRIB command
Lower nibble (RFU)=0</td></tr></table></td></tr>
<tr><td>XX
XX
XX</td><td>Tk</td></tr>
<tr><td>4+N</td><td>UU</td><td>TCK</td><td>Exclusive-oring of all the bytes T0 to Tk</td></tr>
</table>

Example 1: ATR for DESFire = {3B 81 80 01 80 80h} // 6 bytes of ATR

Note: *Use the APDU "FF CA 01 00 00h" to distinguish the ISO 14443A-4 and ISO 14443B-4 PICCs, and retrieve the full ATS if available. ISO 14443A-3 or ISO 14443B-3/4 PICCs do have ATS returned.*

APDU Command = FF CA 01 00 00h

APDU Response = 06 75 77 81 02 80 90 00h

ATS = {06 75 77 81 02 80h}

Example 2: ATR for EZ-link = {3B 88 80 01 1C 2D 94 11 F7 71 85 00 BEh}

Application Data of ATQB = 1C 2D 94 11h

Protocol Information of ATQB = F7 71 85h

MBLI of ATTRIB = 00h

5.0. PCSC API

This section will describe some of the PCSC API for application programming usage. For more details, please refer to Microsoft MSDN Library or PCSC workgroup.

5.1. SCardEstablishContext

The **SCardEstablishContext** function establishes the resource manager context within which database operations are performed.

Refer to: http://msdn.microsoft.com/en-us/library/windows/desktop/aa379479%28v=vs.85%29.aspx

5.2. SCardListReaders

The **SCardListReaders** function provides the list of readers within a set of named reader groups, eliminating duplicates.

The caller supplies a list of reader groups, and receives the list of readers within the named groups. Unrecognized group names are ignored. This function only returns readers within the named groups that are currently attached to the system and available for use.

Refer to: http://msdn.microsoft.com/en-us/library/windows/desktop/aa379793%28v=vs.85%29.aspx

5.3. SCardConnect

The **SCardConnect** function establishes a connection (using a specific resource manager context) between the calling application and a smart card contained by a specific reader. If no card exists in the specified reader, an error is returned.

Refer to: http://msdn.microsoft.com/en-us/library/windows/desktop/aa379473%28v=vs.85%29.aspx

5.4. SCardControl

The **SCardControl** function gives you direct control of the reader. You can call it any time after a successful call to **SCardConnect** and before a successful call to **SCardDisconnect**. The effect on the state of the reader depends on the control code.

Refer to: http://msdn.microsoft.com/en-us/library/windows/desktop/aa379474%28v=vs.85%29.aspx

Note: *Commands from section 7.4 are using this API for sending*

5.5. ScardTransmit

The **SCardTransmit** function sends a service request to the smart card and expects to receive data back from the card.

Refer: http://msdn.microsoft.com/en-us/library/windows/desktop/aa379804%28v=vs.85%29.aspx

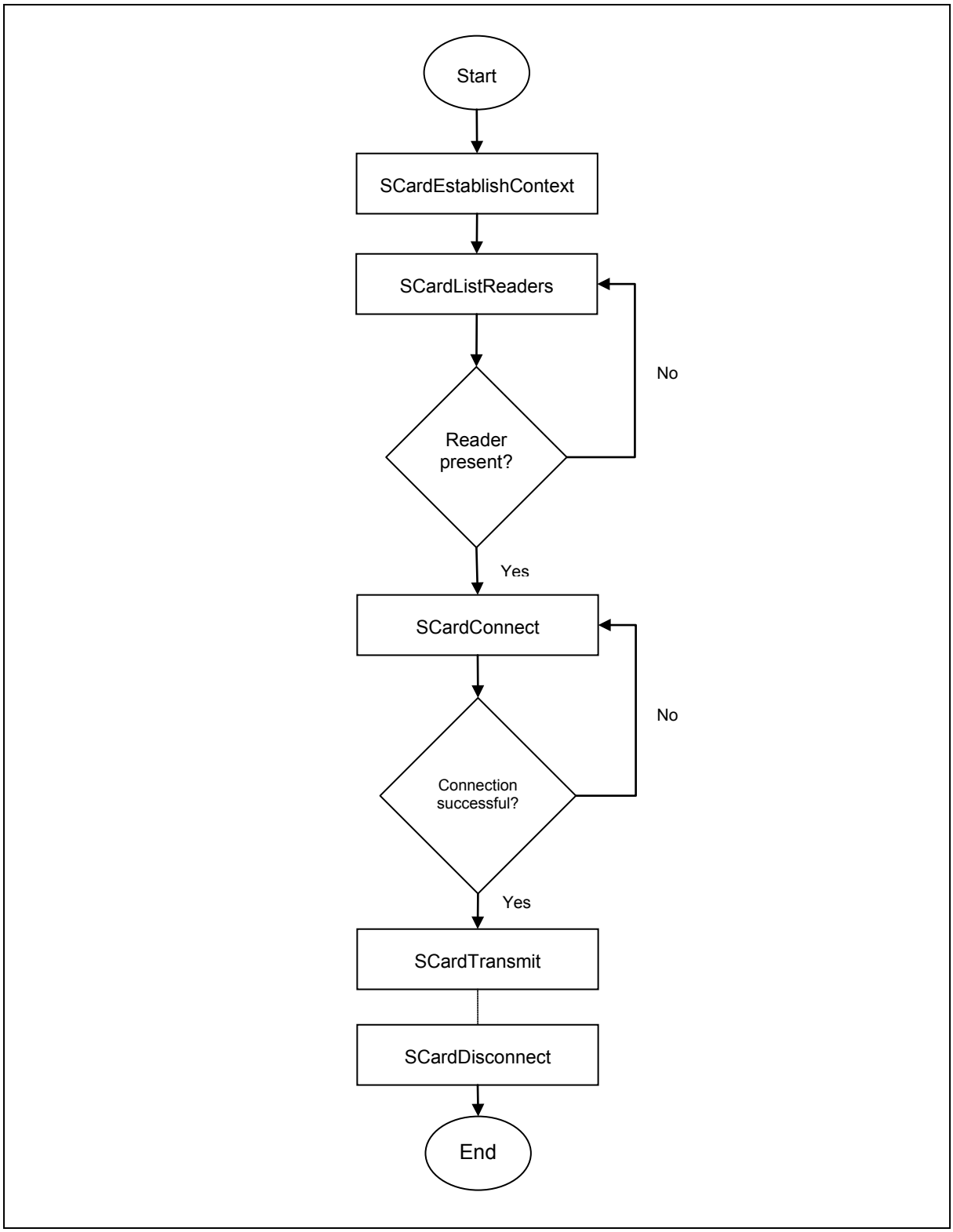
Note: *APDU Commands (i.e. the command sent to connected card and section 7.1) are using this API for sending.*

5.6. ScardDisconnect

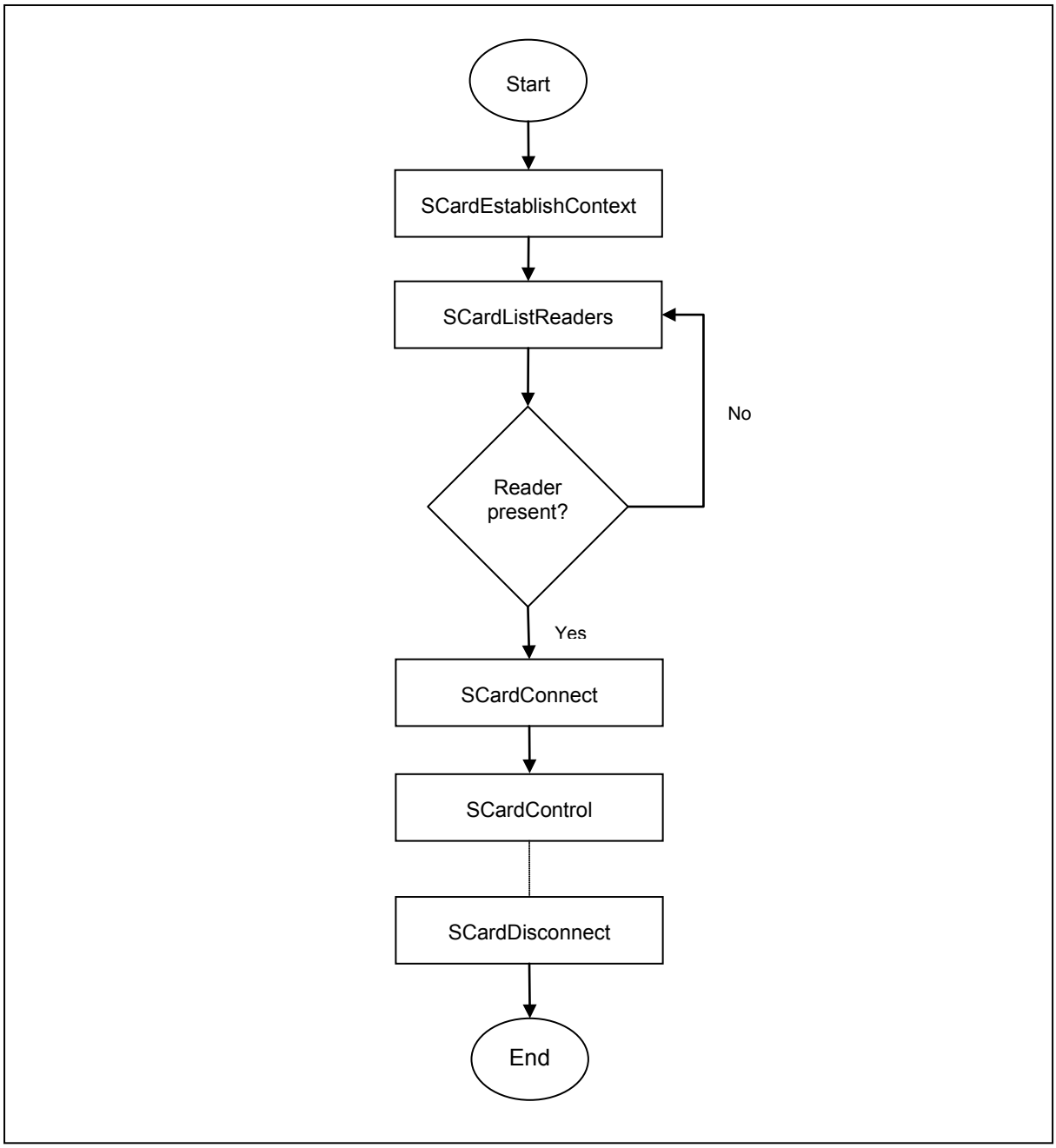
The **SCardDisconnect** function terminates a connection previously opened between the calling application and a smart card in the target reader.

Refer to: http://msdn.microsoft.com/en-us/library/windows/desktop/aa379475%28v=vs.85%29.aspx

5.7. APDU Flow


Start
SCardEstablishContext
SCardListReaders
No
Reader present?
Yes
SCardConnect
No
Connection successful?
Yes
SCardTransmit
SCardDisconnect
End

5.8. Escape Command Flow



6.0. Command Set

6.1. PICC Commands (T=CL Emulation) for Mifare 1K/4K memory cards

6.1.1. Load Authentication Keys

This command is used for loading the authentication keys into the reader. The authentication keys are used to authenticate the particular sector of the Mifare 1K/4K memory card. Two kinds of authentication key locations are provided, volatile and non-volatile key locations respectively.

Load Authentication Keys APDU Format (11 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Load Authentication Keys	FFh	82h	Key Structure	Key Number	06h	Key (6 bytes)

Where:

Key Structure 1 Byte.

00h = Key is loaded into the reader volatile memory.

Other = Reserved.

Key Number 1 Byte.

00 ~ 01h = Volatile memory for storing a temporary key. The key will disappear once the reader is disconnected from the PC. Two volatile keys are provided. The volatile key can be used as a session key for different sessions. *Default Value = {FF FF FF FF FF FFh}*

Key 6 Bytes. The key value loaded into the reader. e.g., {FF FF FF FF FF FFh}

Load Authentication Keys Response Format (2 Bytes)

Response	Data Out	
Result	SW1	SW2

Load Authentication Keys Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

Example:

// Load a key {FF FF FF FF FF FFh} into the volatile memory location 00h.

APDU = {FF 82 00 00 06 FF FF FF FF FF FFh}

6.1.2. Authentication for Mifare 1K/4K

This command uses the keys stored in the reader to do authentication with the Mifare 1K/4K card (PICC). Two types of authentication keys are used: TYPE_A and TYPE_B.

Load Authentication Keys APDU Format (6 Bytes) [Obsolete]

Command	Class	INS	P1	P2	P3	Data In
Authentication	FFh	88h	00h	Block Number	Key Type	Key Number

Load Authentication Keys APDU Format (10 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Authentication	FFh	86h	00h	00h	05h	Authenticate Data Bytes

Authenticate Data Bytes (5 Bytes)

Byte1	Byte 2	Byte 3	Byte 4	Byte 5
Version 01h	00h	Block Number	Key Type	Key Number

Where:

Block Number 1 Byte. The memory block to be authenticated.

For Mifare 1K card, it has totally 16 sectors and each sector consists of four consecutive blocks (e.g., Sector 00h consists of blocks {00h, 01h, 02h and 03h}; sector 01h consists of blocks {04h, 05h, 06h and 07h}; the last sector 0Fh consists of blocks {3Ch, 3Dh, 3Eh and 3Fh}. Once the authentication is done successfully, there is no need to do the authentication again provided that the blocks to be accessed are belonging to the same sector. Please refer to the Mifare 1K/4K specification for more details.

Note: *Once the block is authenticated successfully, all the blocks belonging to the same sector are accessible.*

Key Type 1 Byte.

60h = Key is used as a TYPE A key for authentication.

61h = Key is used as a TYPE B key for authentication.

Key Number 1 Byte.

00 ~ 01h = Volatile memory for storing keys. The keys will disappear when the reader is disconnected from the PC. Two volatile keys are provided. The volatile key can be used as a session key for different sessions.

Load Authentication Keys Response Format (2 Bytes)

Response	Data Out	
Result	SW1	SW2

Load Authentication Keys Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

Sectors (Total 16 sectors. Each sector consists of 4 consecutive blocks)	Data Blocks (3 blocks, 16 bytes per block)	Trailer Block (1 block, 16 bytes)
Sector 0	00 ~ 02h	03h
Sector 1	04 ~ 06h	07h
..		
..		
Sector 14	38 ~ 0Ah	3Bh
Sector 15	3C ~ 3Eh	3Fh

1K Bytes

Table 1: Mifare 1K Memory Map

Sectors (Total 32 sectors. Each sector consists of 4 consecutive blocks)	Data Blocks (3 blocks, 16 bytes per block)	Trailer Block (1 block, 16 bytes)
Sector 0	00 ~ 02h	03h
Sector 1	04 ~ 06h	07h
..		
..		
Sector 30	78 ~ 7Ah	7Bh
Sector 31	7C ~ 7Eh	7Fh

2K Bytes

Sectors (Total 8 sectors. Each sector consists of 16 consecutive blocks)	Data Blocks (15 blocks, 16 bytes per block)	Trailer Block (1 block, 16 bytes)
Sector 32	80 ~ 8Eh	8Fh
Sector 33	90 ~ 9Eh	9Fh
..		
..		
Sector 38	E0 ~ EEh	EFh
Sector 39	F0 ~ FEh	FFh

2K Bytes

Table 2: Mifare 4K Memory Map

Byte Number	0	1	2	3	Page
Serial Number	SN0	SN1	SN2	BCC0	0
Serial Number	SN3	SN4	SN5	SN6	1
Internal/Lock	BCC1	Internal	Lock0	Lock1	2
OTP	OPT0	OPT1	OTP2	OTP3	3
Data read/write	Data0	Data1	Data2	Data3	4
Data read/write	Data4	Data5	Data6	Data7	5
Data read/write	Data8	Data9	Data10	Data11	6
Data read/write	Data12	Data13	Data14	Data15	7
Data read/write	Data16	Data17	Data18	Data19	8
Data read/write	Data20	Data21	Data22	Data23	9
Data read/write	Data24	Data25	Data26	Data27	10
Data read/write	Data28	Data29	Data30	Data31	11
Data read/write	Data32	Data33	Data34	Data35	12
Data read/write	Data36	Data37	Data38	Data39	13
Data read/write	Data40	Data41	Data42	Data43	14
Data read/write	Data44	Data45	Data46	Data47	15

512 bits
or
64 Bytes

Table 3: Mifare Ultralight Memory Map

Examples:

//Authenticate the Block 04h with a {TYPE A, key number 00h}. For PC/SC V2.01, Obsolete.

APDU = {FF 88 00 04 60 00h};

//Authenticate the Block 04h with a {TYPE A, key number 00h}. For PC/SC V2.07

APDU = {FF 86 00 00 05 01 00 04 60 00h}

Note: *Mifare Ultralight does not need to do any authentication. The memory is free to access.*

6.1.3. Read Binary Blocks

This command is used for retrieving a multiple of "data blocks" from the PICC. The data block/trailer block must be authenticated first before executing the "Read Binary Blocks" command.

Read Binary APDU Format (5 Bytes)

Command	Class	INS	P1	P2	Le
Read Binary Blocks	FFh	B0h	00h	Block Number	Number of bytes to read

Where:

Block Number 1 Byte. The starting block.

Number of bytes to read 1 Byte. Multiple of 16 bytes for Mifare 1K/4K or multiple of 4 bytes for Mifare Ultralight.

- Maximum 16 bytes for Mifare Ultralight.
- Maximum 48 bytes for Mifare 1K. (Multiple Blocks Mode; 3 consecutive blocks)
- Maximum 240 bytes for Mifare 4K. (Multiple Blocks Mode; 15 consecutive blocks)

Example 1: 10h (16 bytes). The starting block only. (Single Block Mode)

Example 2: 40h (64 bytes). From the starting block to starting block +3. (Multiple Blocks Mode)

Note: *For safety reason, the Multiple Block Mode is used for accessing data blocks only. The Trailer Block is not supposed to be accessed in Multiple Blocks Mode. Please use Single Block Mode to access the Trailer Block.*

Read Binary Block Response Format (Multiply of 4/16 + 2 Bytes)

Response	Data Out		
Result	Data (Multiply of 4/16 Bytes)	SW1	SW2

Read Binary Block Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

Examples:

// Read 16 bytes from the binary block 04h (Mifare 1K or 4K)

APDU = {FF B0 00 04 10h}

// Read 240 bytes starting from the binary block 80h (Mifare 4K)

// Block 80h to Block 8Eh (15 blocks)

APDU = {FF B0 00 80 F0h}

6.1.4. Update Binary Blocks

This command is used for writing a multiple of "data blocks" into the PICC. The data block/trailer block must be authenticated first before executing the "Update Binary Blocks" command.

Update Binary APDU Format (Multiple of 16 + 5 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Update Binary Blocks	FFh	D6h	00h	Block Number	Number of bytes to update	Block Data (Multiple of 16 Bytes)

Where:

Block Number — 1 Byte. The starting block to be updated.

Number of bytes to update — 1 Byte.

- Multiply of 16 bytes for Mifare 1K/4K or 4 bytes for Mifare Ultralight.
- Maximum 48 bytes for Mifare 1K. (Multiple Blocks Mode; 3 consecutive blocks)
- Maximum 240 bytes for Mifare 4K. (Multiple Blocks Mode; 15 consecutive blocks)

Block Data — Multiple of 16 + 2 Bytes, or 6 bytes. The data to be written into the binary block/blocks.

Example 1: 10h (16 bytes). The starting block only. (Single Block Mode)

Example 2: 30h (48 bytes). From the starting block to starting block +2. (Multiple Blocks Mode)

Note: *For safety reason, the Multiple Block Mode is used for accessing data blocks only. The Trailer Block is not supposed to be accessed in Multiple Blocks Mode. Please use Single Block Mode to access the Trailer Block.*

Update Binary Block Response Codes (2 Bytes)

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

Examples:

// Update the binary block 04h of Mifare 1K/4K with Data {00 01 .. 0Fh}

APDU = {FF D6 00 04 10 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0Fh}

// Update the binary block 04h of Mifare Ultralight with Data {00 01 02 03h}

APDU = {FF D6 00 04 04 00 01 02 03h}

6.1.5. Value Block Operation (INC, DEC, STORE)

The "Value Block Operation" command is used for manipulating value-based transactions. E.g. Increment a value of the value block etc.

Value Block Operation APDU Format (10 Bytes)

Command	Class	INS	P1	P2	Lc	Data In	
Value Block Operation	FFh	D7h	00h	Block Number	05h	VB_OP	VB_Value (4 Bytes) {MSB .. LSB}

Where:

Block Number 1 Byte. The value block to be manipulated.

VB_OP 1 Byte.

00h = Store the VB_Value into the block. The block will then be converted to a value block.

01h = Increment the value of the value block by the VB_Value. This command is only valid for value block.

02h = Decrement the value of the value block by the VB_Value. This command is only valid for value block.

VB_Value 4 Bytes. The value used for value manipulation. The value is a signed long integer (4 bytes).

Example 1: Decimal –4 = {FFh, FFh, FFh, FCh}

VB_Value			
MSB			LSB
FFh	FFh	FFh	FCh

Example 2: Decimal 1 = {00h, 00h, 00h, 01h}

VB_Value			
MSB			LSB
00h	00h	00h	01h

Value Block Operation Response Format (2 Bytes)

Response	Data Out	
Result	SW1	SW2

Value Block Operation Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

6.1.6. Read Value Block

This command is used for retrieving the value from the value block. This command is only valid for value block.

Read Value Block APDU Format (5 Bytes)

Command	Class	INS	P1	P2	Le
Read Value Block	FFh	B1h	00h	Block Number	04h

Where:

Block Number 1 Byte. The value block to be accessed.

Read Value Block Response Format (4 + 2 Bytes)

Response	Data Out		
Result	Value {MSB .. LSB}	SW1	SW2

Where:

Value 4 Bytes. The value returned from the card. The value is a signed long integer (4 bytes).

Example 1: Decimal –4 = {FFh, FFh, FFh, FCh}

Value			
MSB			LSB
FFh	FFh	FFh	FCh

Example: Decimal 1 = {00h, 00h, 00h, 01h}

Value			
MSB			LSB
00h	00h	00h	01h

Read Value Block Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

6.1.7. Copy Value Block

This command is used for copying a value from a value block to another value block.

Copy Value Block APDU Format (7 Bytes)

Command	Class	INS	P1	P2	Lc	Data In	
Value Block Operation	FFh	D7h	00h	Source Block Number	02h	03h	Target Block Number

Where:

Source Block Number 1 Byte. The value of the source value block will be copied to the target value block.

Target Block Number 1 Byte. The value block to be restored. The source and target value blocks must be in the same sector.

Copy Value Block Response Format (2 Bytes)

Response	Data Out	
Result	SW1	SW2

Copy Value Block Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

Examples:

// Store a value "1" into block 05h

APDU = {FF D7 00 05 05 00 00 00 00 01h}

// Read the value block 05h

APDU = {FF B1 00 05 04h}

// Copy the value from value block 05h to value block 06h

APDU = {FF D7 00 05 02 03 06h}

// Increment the value block 05h by "5"

APDU = {FF D7 00 05 05 01 00 00 00 05h}

6.2. Accessing PCSC-compliant tags (ISO 14443-4)

Basically, all ISO 14443-4 compliant cards (PICCs) would understand the ISO 7816-4 APDUs. The ACR1251U-A1 reader just has to communicate with the ISO 14443-4 compliant cards through exchanging ISO 7816-4 APDUs and responses. ACR1251U will handle the ISO 14443 Parts 1-4 Protocols internally.

Mifare 1K, 4K, MINI and Ultralight tags are supported through the T=CL emulation. Just simply treat the Mifare tags as standard ISO 14443-4 tags. For more information, please refer to section 6.1.

ISO 7816-4 APDU Format

Command	Class	INS	P1	P2	Lc	Data In	Le
ISO 7816 Part 4 Command					Length of the Data In		Expected length of the Response Data

ISO 7816-4 Response Format (Data + 2 Bytes)

Response	Data Out		
Result	Response Data	SW1	SW2

Common ISO 7816-4 Response Codes

Results	SW1	SW2	Meaning
Success	90	00h	The operation is completed successfully.
Error	63	00h	The operation is failed.

Typical sequence may be:

1. Present the tag and connect the PICC Interface.
2. Read/Update the memory of the tag.

To do this:

1. Connect the tag.

   The ATR of the tag is 3B 88 80 01 00 00 00 00 33 81 81 00 3Ah.

   In which,

   The Application Data of ATQB = 00 00 00 00, protocol information of ATQB = 33 81 81. It is an ISO 14443-4 Type B tag.

2. Send an APDU, Get Challenge.

   << 00 84 00 00 08h

   >> 1A F7 F3 1B CD 2B A9 58h [90 00h]

   Note: *For ISO 14443-4 Type A tags, the ATS can be obtained by using the APDU "FF CA 01 00 00h."*

Example:

// Read 8 bytes from an ISO 14443-4 Type B PICC (ST19XR08E)

APDU = {80 B2 80 00 08h}

Class = 80h

INS = B2h

P1 = 80h

P2 = 00h

Lc = None

Data In = None

Le = 08h

Answer: 00 01 02 03 04 05 06 07h [$9000h]

6.3. Accessing FeliCa tags

For FeliCa access, the command is different with PCSC-compliant tags and Mifare. The command follows the FeliCa specification with an added header.

FeliCa Command Format

Command	Class	INS	P1	P2	Lc	Data In
FeliCa Command	FFh	00h	00h	00h	Length of the Data In	FeliCa Command (start with Length Byte)

FeliCa Response Format (Data + 2 Bytes)

Response	Data Out
Result	Response Data

Read Memory Block Example:

1. Connect the FeliCa.

   The ATR = 3B 8F 80 01 80 4F 0C A0 00 00 03 06 11 00 3B 00 00 00 00 42h

   In which, 11 00 3Bh = FeliCa

2. Read FeliCa IDM.

   CMD = FF CA 00 00 00h

   RES = [IDM (8bytes)] 90 00h

   e.g., FeliCa IDM = 01 01 06 01 CB 09 57 03h

3. FeliCa command access.

   Example: “Read” Memory Block.

   e.g.

   CMD = FF 00 00 00 10 10 06 01 01 06 01 CB 09 57 03 01 09 01 01 80 00h

   where:

   Felica Command = 10 06 01 01 06 01 CB 09 57 03 01 09 01 01 80 00h

   IDM = 01 01 06 01 CB 09 57 03h

   RES = Memory Block Data

6.4. Peripherals Control

The reader's peripherals control commands are implemented by using *PC_to_RDR_Escape*.

6.4.1. Get Firmware Version

This command is used for getting the reader's firmware message.

Get Firmware Version Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Get Firmware Version	E0h	00h	00h	18h	00h

Get Firmware Version Response Format (5 Bytes + Firmware Message Length)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	Number of bytes to receive	Firmware Version

Example:

Response = E1 00 00 00 0F 41 43 52 31 32 35 31 55 5F 56 32 30 34 2E 30

Firmware Version (HEX) = 41 43 52 31 32 35 31 55 5F 56 32 30 34 2E 30

Firmware Version (ASCII) = "ACR1251U_V204.0"

6.4.2. LED Control

This command is used for controlling the LED's output.

LED Control Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
LED Control	E0h	00h	00h	29h	01h	LED Status

LED Control Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	LED Status

LED Status (1 Byte)

LED Status	Description	Description
Bit 0	RED LED	1 = ON; 0 = OFF
Bit 1	GREEN LED	1 = ON; 0 = OFF
Bit 2 - 7	RFU	RFU

6.4.3. LED Status

This command is used for checking the existing LED's status.

LED Status Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
LED Status	E0h	00h	00h	29h	00h

LED Status Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	LED Status

LED Status (1 Byte)

LED Status	Description	Description
Bit 0	RED LED	1 = ON; 0 = OFF
Bit 1	GREEN LED	1 = ON; 0 = OFF
Bit 2 - 7	RFU	RFU

6.4.4. Buzzer Control

This command is used for controlling the buzzer output.

Buzzer Control Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Buzzer Control	E0h	00h	00h	28h	01h	Buzzer On Duration

Where:

Buzzer On Duration 1 Byte.
00h = Turn OFF
01 to FFh = Duration (unit: 10 ms)

Buzzer Control Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	00h

6.4.5. Buzzer Status

This command is used for checking the existing buzzer status.

Buzzer Status Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Buzzer Status	E0h	00h	00h	28h	00h

Buzzer Status Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	00h

6.4.6. Set LED and Buzzer Status Indicator Behavior

This command is used for setting the behaviors of LEDs and buzzer as status indicators.

Note: *The setting will be saved into non-volatile memory.*

Set LED and Buzzer Status Indicator Behavior Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Set LED and Buzzer Status Indicator Behavior	E0h	00h	00h	21h	01h	Behavior

Behavior (1 Byte)

Behavior	MODE	Description
Bit 0	SAM Activation Status LED	To show the activation status of the SAM interface. 1 = Enable; 0 =Disable
Bit 1	PICC Polling Status LED	To show the PICC Polling Status. 1 = Enable; 0 =Disable
Bit 2	PICC Activation Status LED	To show the activation status of the PICC interface 1 = Enable; 0 =Disable
Bit 3	Card Insertion and Removal Events Buzzer	To make a beep whenever a card insertion or removal event is detected. (For PICC) 1 = Enable; 0 =Disabled
Bit 4 – 6	RFU	RFU
Bit 7	Card Operation Blinking LED	To blink the LED whenever the card (PICC) is being accessed.

Note: *Default value of behavior = 8Fh*

Set LED and Buzzer Status Indicator Behaviors Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Default Behaviors

6.4.7. Read LED and Buzzer Status Indicator Behavior

This command is used for reading the current default behaviors of LEDs and buzzer.

Read LED and Buzzer Status Indicator Behavior Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Read LED and Buzzer Status Indicator Behavior	E0h	00h	00h	21h	00h

Read LED and Buzzer Status Indicator Behavior Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Behaviors

Behavior (1 Byte)

Behavior	MODE	Description
Bit 0	SAM Activation Status LED	To show the activation status of the SAM interface. 1 = Enable; 0 =Disable
Bit 1	PICC Polling Status LED	To show the PICC polling status. 1 = Enable; 0 =Disable
Bit 2	PICC Activation Status LED	To show the activation status of the PICC interface. 1 = Enable; 0 =Disable
Bit 3	Card Insertion and Removal Events Buzzer	To make a beep whenever a card insertion or removal event is detected. (For PICC) 1 = Enable; 0 =Disabled
Bit 4 – 6	RFU	RFU
Bit 7	Card Operation Blinking LED	To make the LED blink whenever the card (PICC) is being accessed.

Note: *Default value of Behavior = 8Fh.*

6.4.8. Set Automatic PICC Polling

This command is used for setting the reader's polling mode.

Whenever the reader is connected to the PC, the PICC polling function will start the PICC scanning to determine if a PICC is placed on/removed from the built-antenna.

You can send a command to disable the PICC polling function. The command is sent through the PCSC Escape command interface. To meet the energy saving requirement, special modes are provided for turning off the antenna field whenever the PICC is inactive, or no PICC is found. The reader will consume less current in power saving mode.

Note: *The setting will be saved into non-volatile memory*

Set Automatic PICC Polling Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Set Automatic PICC Polling	E0h	00h	00h	23h	01h	Polling Setting

Set Automatic PICC Polling Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Polling Setting

Polling Setting (1 Byte)

Polling Setting	Mode	Description
Bit 0	Auto PICC Polling	1 = Enable; 0 =Disable
Bit 1	Turn off Antenna Field if no PICC found	1 = Enable; 0 =Disable
Bit 2	Turn off Antenna Field if the PICC is inactive.	1 = Enable; 0 =Disable
Bit 3	Activate the PICC when detected.	1 = Enable; 0 =Disable
Bit 5 .. 4	PICC Poll Interval for PICC	<Bit 5 – Bit 4> <0 – 0> = 250 ms <0 – 1> = 500 ms <1 – 0> = 1000 ms <1 – 1> = 2500 ms
Bit 6	RFU	
Bit 7	Enforce ISO 14443A Part 4	1= Enable; 0= Disable.

Note: *Default value of Polling Setting = 8Fh.*

Reminders:

1. *It is recommended to enable the option "Turn Off Antenna Field if the PICC is inactive", so that the "Inactive PICC" will not be exposed to the field all the time to prevent the PICC from*

"warming up".

2. *The longer the PICC Poll Interval, the more efficient of energy saving. However, the response time of PICC Polling will become longer. The Idle Current Consumption in Power Saving Mode is about 60 mA, while the Idle Current Consumption in Non-Power Saving mode is about 130mA.* ***Note:*** *Idle Current Consumption = PICC is not activated.*
3. *The reader will activate the ISO 14443A-4 mode of the "ISO 14443A-4 compliant PICC" automatically. Type B PICC will not be affected by this option.*
4. *The JCOP30 card comes with two modes: ISO 14443A-3 (Mifare 1K) and ISO 14443A-4 modes. The application has to decide which mode should be selected once the PICC is activated.*

6.4.9. Read Automatic PICC Polling

This command is used for checking the current PICC polling setting.

Read Automatic PICC Polling Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Read Automatic PICC Polling	E0h	00h	00h	23h	00h

Read the Configure Mode Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Polling Setting

Polling Setting (1 Byte)

Polling Setting	Mode	Description
Bit 0	Auto PICC Polling	1 = Enable; 0 =Disable
Bit 1	Turn off Antenna Field if no PICC found	1 = Enable; 0 =Disable
Bit 2	Turn off Antenna Field if the PICC is inactive.	1 = Enable; 0 =Disable
Bit 3	Activate the PICC when detected.	1 = Enable; 0 =Disable
Bit 5 .. 4	PICC Poll Interval for PICC	<Bit 5 – Bit 4> <0 – 0> = 250 ms <0 – 1> = 500 ms <1 – 0> = 1000 ms <1 – 1> = 2500 ms
Bit 6	RFU	
Bit 7	Enforce ISO14443A Part 4	1= Enable; 0= Disable.

Note: *Default value of Polling Setting = 8Fh*

6.4.10. Set PICC Operating Parameter

This command is used for setting the PICC operating parameter.

Note: *The setting will be saved into non-volatile memory.*

Set the PICC Operating Parameter Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Set the PICC Operating Parameter	E0h	00h	00h	20h	01h	Operation Parameter

Set the PICC Operating Parameter Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1	00h	00h	00h	01h	Operation Parameter

Operating Parameter (1 Byte)

Operating Parameter	Parameter	Description	Option
Bit 0	ISO 14443 Type A	The Tag Types to be detected during PICC Polling.	1 = Detect 0 = Skip
Bit 1	ISO 14443 Type B		1 = Detect 0 = Skip
Bit 2	FeliCa 212 kbps		1 = Detect 0 = Skip
Bit 3	FeliCa 424 kbps		1 = Detect 0 = Skip
Bit 4	Topaz		1 = Detect 0 = Skip
Bit 5 - 7	RFU	RFU	RFU

Note: *Default value of Operation Parameter = 1Fh*

6.4.11. Read PICC Operating Parameter

This command is used for checking the current PICC operating parameter.

Read the PICC Operating Parameter Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Read the PICC Operating Parameter	E0h	00h	00h	20h	00h

Read the PICC Operating Parameter Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Operation Parameter

Operating Parameter (1 Byte)

Operating Parameter	Parameter	Description	Option
Bit 0	ISO 14443 Type A	The Tag Types to be detected during PICC polling.	1 = Detect 0 = Skip
Bit 1	ISO 14443 Type B		1 = Detect 0 = Skip
Bit 2	FeliCa 212 kbps		1 = Detect 0 = Skip
Bit 3	FeliCa 424 kbps		1 = Detect 0 = Skip
Bit 4	Topaz		1 = Detect 0 = Skip
Bit 5 - 7	RFU	RFU	RFU

6.4.12. Set Auto PPS

Whenever a PICC is recognized, the reader will try to change the communication speed between the PCD and PICC defined by the maximum connection speed. If the card does not support the proposed connection speed, the reader will try to connect the card with a slower speed setting.

Note: *The setting will be saved into non-volatile memory.*

Set Auto PPS Format (7 Bytes)

Command	Class	INS	P1	P2	Lc	Data In	
Set Auto PPS	E0h	00h	00h	24h	02h	Max Tx Speed	Max Rx Speed

Set Auto PPS Response Format (9 Bytes)

Response	Class	INS	P1	P2	Le	Data Out			
Result	E1h	00h	00h	00h	04h	Max Tx Speed	Current Tx Speed	Max Rx Speed	Current Rx Speed

Where:

Max Tx Speed 1 Byte. Maximum Transmission Speed.

Max Rx Speed 1 Byte. Maximum Receiving Speed.

Current Tx Speed 1 Byte. Current Transmission Speed.

Current Rx Speed 1 Byte. Current Receiving Speed.

Value can be:

106k bps = 00h (default setting)

212k bps = 01h

424k bps = 02h

848k bps = 03h

No Auto PPS = FFh

Notes:

1. *Normally, the application should know the maximum connection speed of the PICCs being used. The environment also affects the maximum achievable speed. The reader just uses the proposed communication speed to talk with the PICC. The PICC will become inaccessible if the PICC or environment does not meet the requirement of the proposed communication speed.*
2. *The reader supports different speed between sending and receiving.*

6.4.13. Read Auto PPS

This command is used for checking the current auto PPS setting.

Read Auto PPS Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Read Auto PPS	E0h	00h	00h	24h	00h

Set Auto PPS Response Format (9 Bytes)

Response	Class	INS	P1	P2	Le	Data Out			
Result	E1h	00h	00h	00h	04h	Max Tx Speed	Current Tx Speed	Max Rx Speed	Current Rx Speed

Where:

Max Tx Speed 1 Byte. Maximum Transmission Speed.

Max Rx Speed 1 Byte. Maximum Receiving Speed.

Current Tx Speed 1 Byte. Current Transmission Speed.

Current Rx Speed 1 Byte. Current Receiving Speed.

Value can be:

106k bps = 00h (default setting)

212k bps = 01h

424k bps = 02h

848k bps = 03h

No Auto PPS = FFh

6.4.14. Antenna Field Control

This command is used for turning on/off the antenna field.

Antenna Field Control Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
Antenna Field Control	E0h	00h	00h	25h	01h	Status

Antenna Field Control Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Status

Where:

Status 1 Byte.

01h = Enable Antenna Field

00h = Disable Antenna Field

Note: *Make sure the Auto PICC Polling is disabled first before turning off the antenna field.*

6.4.15. Read Antenna Field Status

This command is used for checking the current antenna field status.

Read Antenna Field Status Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Read Antenna Field Status	E0h	00h	00h	25h	00h

Read Antenna Field Status Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Status

Where:

Status 1 Byte.

00h = PICC Power Off

01h = PICC Idle [Ready to Poll Contactless Tag, but not detected]

02h = PICC Ready [PICC Request (Refer to ISO 14443) Success, i.e. Contactless Tag Detected]

03h = PICC Selected [PICC Select (Refer to ISO 14443) Success]

04h = PICC Activate [PICC Activation (Refer to ISO 14443) Success, Ready for APDU Exchange]

6.4.16. Read User Extra Guard Time

This command is used for reading the set extra guard time for SAM communication.

Read User Extra Guard Time Format (6 Bytes)

Command	Class	INS	P1	P2	Lc
Read User Extra Guard Time	E0h	00h	00h	2Eh	00h

Read User Extra Guard Time Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	UserGuardTime

Where:

UserGuardTime 1 Byte. User guard time value.

6.4.17. "616C" Auto Handle Option Setting

(Optional for T=0 ACOS5)

This command is used for setting the "616C" auto handle option.

Note: *The setting will be saved into non-volatile memory.*

"616C" Auto Handle Option Setting Format (6 Bytes)

Command	Class	INS	P1	P2	Lc	Data In
"616C" Auto Handle Option Setting	E0h	00h	00h	32h	01h	Option

"616C" Auto Handle Option Setting Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Option

Where:

Option 1 Byte. User guard time value.
FFh = Enable "616C" Auto Handle
00h = Disable "616C" Auto Handle (Default)

6.4.18. Read "616C" Auto Handle Option

This command is used for reading the "616C" auto handle option.

Read "616C" Auto Handle Option Format (6 Bytes)

Command	Class	INS	P1	P2	Lc
Read "616C" Auto Handle Option	E0h	00h	00h	32h	00h

Read “616C” Auto Handle Option Response Format (6 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	01h	Option

Where:

Option 1 Byte. User guard time value.

FFh = Enable “616C” Auto Handle

00h = Disable “616C” Auto Handle (Default)

6.5. ACR122U Compatible Commands

6.5.1. Bi-color LED and Buzzer Control

This command is used for controlling the states of the bi-color LED and buzzer.

Bi-color LED and Buzzer Control Command Format (9 Bytes)

Command	Class	INS	P1	P2	Lc	Data In (4 Bytes)
Bi-color LED and Buzzer Control	FFh	00h	40h	LED State Control	04h	Blinking Duration Control

P2 LED State Control

Bi-color LED and Buzzer Control Format (1 Byte)

CMD	Item	Description
Bit 0	Final Red LED State	1 = On; 0 = Off
Bit 1	Final Green LED State	1 = On; 0 = Off
Bit 2	Red LED State Mask	1 = Update the State 0 = No change
Bit 3	Green LED State Mask	1 = Update the State 0 = No change
Bit 4	Initial Red LED Blinking State	1 = On; 0 = Off
Bit 5	Initial Green LED Blinking State	1 = On; 0 = Off
Bit 6	Red LED Blinking Mask	1 = Blink 0 = Not Blink
Bit 7	Green LED Blinking Mask	1 = Blink 0 = Not Blink

Data In Blinking Duration Control

Bi-color LED Blinking Duration Control Format (4 Bytes)

Byte 0	Byte 1	Byte 2	Byte 3
T1 Duration Initial Blinking State (unit = 100 ms)	T2 Duration Toggle Blinking State (unit = 100 ms)	Number of repetition	Link to Buzzer

Where:

Byte 3 Link to Buzzer. Control the buzzer state during the LED Blinking.

00h = The buzzer will not turn on.

01h = The buzzer will turn on during the T1 Duration.

02h = The buzzer will turn on during the T2 Duration.

03h = The buzzer will turn on during the T1 and T2 Duration.

Data Out SW1 SW2. Status Code returned by the reader.

Status Code

Results	SW1	SW2	Meaning
Success	90h	Current LED State	The operation is completed successfully.
Error	63	00h	The operation is failed.

Current LED State (1 Byte)

Status	Item	Description
Bit 0	Current Red LED	1 = On; 0 = Off
Bit 1	Current Green LED	1 = On; 0 = Off
Bits 2 – 7	Reserved	

Reminders:

1. *The LED State operation will be performed after the LED Blinking operation is completed.*
2. *The LED will not change if the corresponding LED Mask is not enabled.*
3. *The LED will not blink if the corresponding LED Blinking Mask is not enabled. Also, the number of repetition must be greater than zero.*
4. *T1 and T2 duration parameters are used for controlling the duty cycle of LED blinking and Buzzer Turn-On duration. For example, if T1=1 and T2=1, the duty cycle = 50%.* ***Note:*** *Duty Cycle = T1 / (T1 + T2).*
5. *To control only the buzzer, just set the P2 "LED State Control" to zero.*
6. *To make the buzzer operate, the "number of repetition" must greater than zero.*
7. *To control only the LED, just set the parameter "Link to Buzzer" to zero.*

6.5.2. Get Firmware Version

This command is used for retrieving the firmware version of the reader.

Get Firmware Version Command Format (5 Bytes)

Command	Class	INS	P1	P2	Le
Get Firmware	FFh	00h	48h	00h	00h

Get Firmware Version Response Format (X bytes)

Response	Data Out
Result	Firmware Version

Example:

Response = 41 43 52 31 32 35 31 55 5F 56 32 30 34 2E 30 (Hex) = ACR1251U_V204.0 (ASCII)

6.5.3. Get PICC Operating Parameter

This command is used for getting the PICC operating parameter of the reader.

Get the PICC Operating Parameter Command Format (5 Bytes)

Command	Class	INS	P1	P2	Le
Get PICC Operation Parameter	FFh	00h	50h	00h	00h

Get the PICC Operating Parameter Response Format (2 byte)

Response	Data Out	
Result	90h	PICC Operating Parameter

PICC Operating Parameter

Bit	Parameter	Description	Option
7	Auto PICC Polling	To enable the PICC polling.	1 = Enable 0 = Disable
6	Auto ATS Generation	To issue ATS request whenever an ISO 14443-4 Type A tag is activated.	1 = Enable 0 = Disable
5	Polling Interval	To set the time interval between successive PICC polling.	1 = 250 ms 0 = 500 ms
4	FeliCa 424 kbps	The Tag Types to be detected during PICC polling.	1 = Detect 0 = Skip
3	FeliCa 212 kbps		1 = Detect 0 = Skip
2	Topaz		1 = Detect 0 = Skip
1	ISO 14443 Type B		1 = Detect 0 = Skip
0	ISO 14443 Type A ***Note:*** *To detect the Mifare tags, the Auto ATS Generation must be disabled first.*		1 = Detect 0 = Skip

6.5.4. Set PICC Operating Parameter

This command is used for setting the PICC operating parameter of the reader.

Set PICC operation Parameter Command Format (5 Bytes)

Command	Class	INS	P1	P2	Le
Set PICC operation Parameter	FFh	00h	51h	PICC Operating Parameter	00h

Set PICC operation Parameter Response Format (2 byte)

Response	Data Out	
Result	90h	PICC Operating Parameter

PICC Operating Parameter

Bit	Parameter	Description	Option
7	Auto PICC Polling	To enable the PICC polling.	1 = Enable 0 = Disable
6	Auto ATS Generation	To issue ATS request whenever an ISO 14443-4 Type A tag is activated.	1 = Enable 0 = Disable
5	Polling Interval	To set the time interval between successive PICC polling.	1 = 250 ms 0 = 500 ms
4	FeliCa 424 kbps	The Tag Types to be detected during PICC polling.	1 = Detect 0 = Skip
3	FeliCa 212 kbps		1 = Detect 0 = Skip
2	Topaz		1 = Detect 0 = Skip
1	ISO 14443 Type B		1 = Detect 0 = Skip
0	ISO 14443 Type A ***Note:*** *To detect the Mifare tags, the Auto ATS Generation must be disabled first.*		1 = Detect 0 = Skip

6.6. NFC Peer-to-Peer Related Commands

6.6.1. SNEP Message

This command is used for setting the SNEP Message which will be sent after executing the Enter Initiator Mode command.

SNEP Message Command Format (X Bytes)

Command	Class	INS	P1	P2	Lc	Data In
SNEP Message	E0h	00h	00h	50h	SNEP Len	SNEP Message (Max 100Bytes)

SNEP Message Response Format (X Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	SNEP Len	SNEP Message

For the data format, please refer to specification “NFC Forum NFC Data Exchange Format (NDEF) 1.0.”

Example:

SNEP Message = {D1 02 0F 53 70 D1 01 0B 55 01 61 63 73 2E 63 6F 6D 2E 68 6Bh}

Offset	Content	Length	Description
0	D1	1	NDEF header. TNF = 0x01, SR=1, MB=1, ME=1
1	02	1	Record name length (2 bytes)
2	0F	1	Length of the Smart Poster data (15 bytes)
3	53 70 (“Sp”)	2	Record name
5	D1	1	NDEF header. TNF = 0x01, SR=1, MB=1, ME=1
6	01	1	Record name length (1 byte)
7	0B	1	The length of the URI payload (11 bytes)
8	55 (“U”)	1	Record type: “U”
9	01	1	Abbreviation: “http://www.”
10	61 63 73 2E 63 6F 6D 2E 68 6B	10	The URL itself. “acs.com.hk”

6.6.2. Set Initiator Mode Timeout

This command is used to set the timeout for Initiator Mode. Once the reader enters Initiator, it will retry 5 times (each time with 250ms interval) in order to success exchange SNEP message.

Set Initiator Mode Timeout Command Format (7 Bytes)

Command	Class	INS	P1	P2	Lc	Data In	
Enter Initiator Mode	E0h	00h	00h	41h	02h	Timeout (MSB)	Timeout (LSB)

Set Initiator Mode Timeout Response Format (7 Bytes)

Response	Class	INS	P1	P2	Le	Data Out	
Result	E1	00h	00h	00h	02h	Timeout (MSB)	Timeout (LSB)

Where:

Timeout 2 Bytes. Timeout for Initiator Mode (unit = 10 ms)

6.6.3. Enter Initiator Mode

This command is used for setting the reader into Initiator Mode to send out SNEP message.

Enter Initiator Mode Command Format (8 Bytes)

Command	Class	INS	P1	P2	Lc	Data In		
Enter Initiator Mode	E0h	00h	00h	40h	03h	NFCMode	OpMode	Speed

Enter Initiator Mode Response Format (8 Bytes)

Response	Class	INS	P1	P2	Le	Data Out		
Result	E1h	00h	00h	00h	03h	NFCMode	OpMode	Speed

Where:

NFCMode 1 Byte. NFC Device Mode.
06h = Peer-to-Peer Initiator Mode
Other = Card Read/Write Mode

OpMode 1 Byte. Active Mode/Passive Mode.
01h = Active Mode
02h = Passive Mode

Speed 1 Byte. Communication speed.
01h = 106 kbps
02h = 212 kbps
03h = 424 kbps

After executing Enter Initiator Mode, the reader will wait for the NFC device, which in Target Mode, will present and send out the pre-set SNEP Message to it. The reader will stop all other tasks until the SNEP Message is sent successfully.

6.6.4. Enter Target Mode

This command is used for setting the reader into Target Mode to receive SNEP message.

Enter Target Mode Command Format (11 Bytes)

Command	Class	INS	P1	P2	Lc	Data In					
Enter Initiator Mode	E0h	00h	00h	99h	06h	98h	01h	NFCMode	1Ah	01h	Conductance

Enter Target Mode Response Format (11 Bytes)

Response	Class	INS	P1	P2	Le	Data Out					
Result	E1h	00h	00h	00h	06h	98h	01h	NFCMode	1Ah	01h	Conductance

Where:

NFCMode 1 Byte. NFC Device Mode.
04h = Peer-to-Peer Target Mode
00h = Card Read/Write Mode

Conductance 1 Byte. Antenna conductance setting.

After executing Enter Target Mode, the reader will wait for NFC device, which in Initiator Mode, will present and receive the SNEP Message.

6.6.5. Get Received Data

This command is used for getting the data received from NFC initiator device.

Enter Target Mode Command Format (5 Bytes)

Command	Class	INS	P1	P2	Lc
Enter Initiator Mode	E0h	00h	00h	99h	C0h

Enter Target Mode Response Format (11 Bytes)

Response	Class	INS	P1	P2	Le	Data Out
Result	E1h	00h	00h	00h	SNEP Message Len	SNEP Message

Where:

SNEP Message Len 1 Byte. Length of the received SNEP Message.

SNEP Message N Bytes. Received SNEP message.